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Books and chapter edited volumes/books published and paper published in national and international conference proceeding

Index

Sl. No	Particulars	Page. No
1	Summary	2
2	Books and chapter edited volumes/books published and paper published in national and international conference proceeding 2022-2023	3


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Summary

In academic year 2022-23, the faculty of The Oxford College of Engineering has presented 17 papers in international conferences and published 12 Book/Book Chapters

Sl. No	Academic Year	Conferences		Book
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1	2022-23	0	17	12
Total				29



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Sl . N o.	Name of the teacher	Title of the book/chapters published	Title of the paper	Title of the proceedings of the conference	Name of the conference	National / International	Year of publication	ISBN/ISSN number of the proceeding	Affiliating Institute at the time of publication	Name of the publisher
1	Dr E Saravana Kumar	Teach Yourself Operating Systems	NA	NA	NA	National	2022	B0B8CC36Y1	The Oxford College of Engineering	Amazon - Kindle
2	J Jesy Janet Kumari	Electronic Circuits Analysis & its Simulation with PSPICE	NA	NA	NA	National	2023	ISBN-13: 9789355359506	The Oxford College of Engineering	Amazon - Kindle
3	Raghu Ramamooorthy, E. Saravana Kumar, R. Ch. A. Naidu, Shruthi	NA -	Hybrid MultiHop Routing Mechanism with Intelligent Transportation System architecture for Efficient Routing in VANETs	Second IEEE International Conference CENTCON-2022	Second IEEE International Conference CENTCON-2022	International	2022	ISBN: 978-1-6654-6374-4	The Oxford College of Engineering	IEEE



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4	J Jesy Janet Kumari	NA	Medical Assistance for Alzheimer's Disease Using Smart Specs	4th International Conference I4C2022 (21st-23rd December 2022)	4th International Conference I4C2022 (21st-23rd December 2022)	International	2022	979-8-3503-9747-5	The Oxford College of Engineering	IEEE
5	Sathya M	NA	An Empirical Study on E-Commerce site using unique AI based features and Data science tools	4th International Conference on Electronics and Sustainable Communication System - ICESC 2023, 6th - 8th July.	4th International Conference on Electronics and Sustainable Communication System - ICESC 2023, 6th - 8th July.	International	2023	ISBN: 979-8-3503-0008-6	The Oxford College of Engineering	IEEE



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6	Ramya Sri M	- NA	An Empirical Study on E-Commerce site using unique AI based features and Data science tools	4th International Conference on Electronics and Sustainable Communication System - ICESC 2023, 6th - 8th July.	4th International Conference on Electronics and Sustainable Communication System - ICESC 2023, 6th - 8th July.	International	2023	ISBN: 979-8-3503-0008-6	The Oxford College of Engineering	IEEE
7	Lenish Pramiee J	PROBLEM SOLVING AND PYTHON PROGRAMMING	NA	NA	NA	National	2023	ISBN-13:978-93-5577-603-7	The Oxford College of Engineering	Charulatha Publications
8	Manjula L	PROBLEM SOLVING AND PYTHON PROGRAMMING	NA	NA	NA	National	2023	ISBN-13:978-93-5577-603-7	The Oxford College of Engineering	Charulatha Publications



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9	Vinotha D	NA	Trust Value-Based Energy-Efficient Routing to Improve Lifetime in Heterogeneous WBAN	International Conference on Artificial Intelligence and Application(ICAIA) Alliance Technology Conference	International Conference on Artificial Intelligence and Application(ICAIA) Alliance Technology Conference	International	2023	ISBN:978-1-6654-5628-9	The Oxford College of Engineering	IEEE
10	Vinotha D	NA	Prediction of Infant Growth using the Random Forest Algorithm	3rd International Conference on Advance Computing and Innovative Technologies in Engineering (ICACITE)	3rd International Conference on Advance Computing and Innovative Technologies in Engineering (ICACITE)	International	2023	ISBN:979-8-3503-9927-1	The Oxford College of Engineering	IEEE



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11	Dr, E. Saravana Kumar	NA	IoT based Innovative Teaching Learning using Smart Class Rooms	2023 International Conference on Sustainable Computing and Data Communication Systems (ICSCDS)	2023 International Conference on Sustainable Computing and Data Communication Systems (ICSCDS)	International	2023	10.1109/ICSCDS56580.2023.10104589	The Oxford College of Engineering	IEEE
12	Dr. Vanaja Roseline	Internet of Everything :Smart Sensing Technologies	NA	NA	NA	international	2022	978-1-68507-865-2	The Oxford College of Engineering	Nova publishers
13	Ms .Diana	The APT Cyber Warriors With TTP Weapons to Battle: An Review on IoT and Cyber Twin	NA	NA	NA	international	2022	9781668457221	The Oxford College of Engineering	IGI global



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14	Ranjith B Gowda; Vilas T, V; Komal G D; Venkatesh Badageri; Preeta Sharan; Ciro Rodriguez	NA	Bacterial Detection in Contaminated Water Using a Photonic Crystal Sensor	2023 International Conference on Smart Systems for applications in Electrical Sciences (ICSSSES)	2023 International Conference on Smart Systems for applications in Electrical Sciences (ICSSSES)	International	2023	979-8-3503-4729-6	The Oxford College of Engineering	IEEE
15	Suchandana Mishra; V. Sharmili; Saptha Sree M.; Sneha S.; Saara K.; Preeta Sharan	NA	Numerical Analysis for Flat Wheel Detection at Different Wagon Load	2023 10th International Conference on Computing for Sustainable Global Development (INDIACom)	2023 International Conference on Smart Systems for applications in Electrical Sciences (ICSSSES)	International	2023	978-93-80544-47-2	The Oxford College of Engineering	IEEE
16	Neil Roy, Sandip Kumar Roy, Preeta Sharan	NA	Effective Brain Tumor Segmentation for MRI Image Analysis using Dual Attention	2023 10th International Conference on Computing for Sustainable Global Development (INDIACom)	2023 10th International Conference on Computing for Sustainable Global Development (INDIACom)	International	2023	978-1-6654-7703-1	The Oxford College of Engineering	IEEE



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			Network based YOLACT ++							
17		NA	FEM Analysis of Railway Brake Disc for Safety of Train	2023 10th International Conference on Computing for Sustainable Global Development (INDIACom	2023 10th International Conference on Computing for Sustainable Global Development (INDIACom	International	2023	978-93-80544-47-2	The Oxford College of Engineering	IEEE
18	Roberto Santos, Paula Santos, Preeta Sharan, Ciro Rodriguez	NA	Technological Coefficient to Improve Research Development and Innovation Factors in the World	International Conference on Intelligent Technologies	International Conference on Intelligent Technologies	International	2023	978-981-99-1912-3	The Oxford College of Engineering	IEEE



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19	Anup M Upadhyaya, Preeta Sharan	Photonic MEMS Sensor for Biomedical Applications	NA	NA	NA	International	2023	9781003331681	The Oxford College of Engineering	Taylor and Francis
20	Preeta Sharan	Distributed Bragg Reflector Biosensor for Medical Application	NA	NA	NA	International		9781003331681	The Oxford College of Engineering	Taylor and Francis
21	Jayakumar N, Devi Vighneshwari, Nisha C Rani	Artificial Intelligence Based Smart Power Systems	NA	NA	NA	International	Dec-22	9781119893967	The Oxford College of Engineering	Wiley-IEEE Press
22	Resna S R	NA	Space vector Pulse Width Modulation with 7 Level ANPC Converters for Capacitor Voltage Balancing	3rd International Conference on Innovative Practices in Technology and Management (ICIPTM)	3rd International Conference on Innovative Practices in Technology and Management (ICIPTM)	International	Feb-23	979-8-3503-3624-5	The Oxford College of Engineering	IEEE



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23	Anup M Upadhyaya	NA	Design and Analysis of Pressure Sensor based on Micro Hole Photonic Crystal Slab	2023 10th International Conference on Computing for Sustainable Global Development (INDIACom)	2023 10th International Conference on Computing for Sustainable Global Development (INDIACom)	International	2023	978-93-80544-47-2	The Oxford College of Engineering	IEEE
24	Harshitha N	NA	Light Transmitting Concrete	international conference on advances in civil engineering (icace-ewit-2022)	international conference on advances in civil engineering (icace-ewit-2022)	International	2022	NA	The Oxford College of Engineering	Google Scholar
25	Pashant Hatewar	NA	the behavior of residential building under earthquake loads with and without shear wall	international conference on advances in civil engineering (icace-ewit-2022)	international conference on advances in civil engineering (icace-ewit-2022)	International	2022	NA	The Oxford College of Engineering	Google Scholar



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26	Mr.jaideep R	NA	ROBOTIC HAND GESTURE	ICGCP	ICGCP	International	2023	ISBN: 9798392733033	The Oxford College of Engineering	Google Scholar
27	Dharamvir	Research Methodology : A Prospective	NA	NA	NA	National	2022	978-93-5515-734-8	The Oxford College of Engineering	Book Rivers
28	Dharamvir	New and Forthcoming : Cloud Computing	NA	NA	NA	National	2022	9789360000000	The Oxford College of Engineering	Book Rivers
29	Dr. Shipra Bhati	Environmental Pollution- Effects and Causes	NA	NA	NA	National	2022	978-93-95936-13-2	The Oxford College of Engineering	AGPH Books

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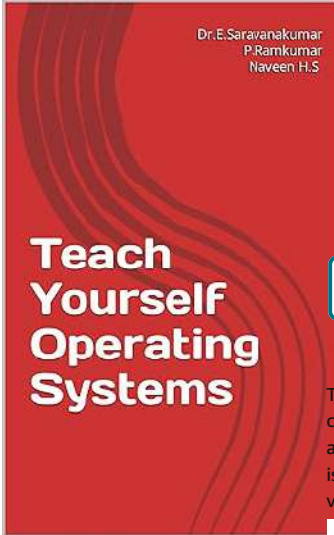
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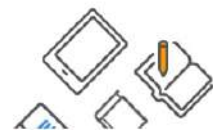
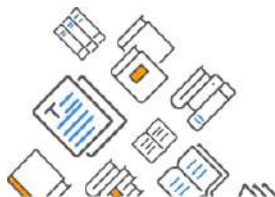
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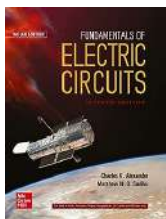
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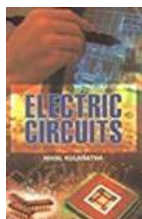


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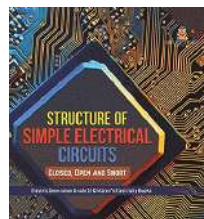


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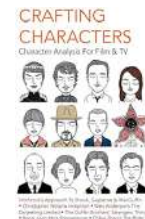
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Abstract



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Document Sections

- I. Introduction
- II. Related Work
- III. Proposed Hmrm-Its Architecture
- IV. Simulation Results
- V. Conclusion

Abstract: Intelligent Transportation Systems (ITS) are required for efficient vehicle communication in the smart city. The goal of ITS was to provide a broad range of services in transportation, safety, comfort, commercial, mobility, and connectivity applications. In this era, road traffic is a major annoyance. The provision of real-time traffic information to drivers, in conjunction with a navigation system, can enable vehicles to choose the best route. To support ITS, this work proposes a Hybrid Multi-hop Routing Mechanism with Intelligent Transportation System (HMRM-ITS) for efficient communication among vehicles in vehicular ad hoc networks (VANETs). The proposed HMRM-ITS employs the multi-hop routing concept to enable vehicles to improve their driving performance and road safety. Furthermore, the proposed HMRM-ITS allows the transportation organization to communicate instantly between vehicles to Road-Side Units (RSUs), as well as vehicles-traffic servers in an efficient manner. The proposed mechanism enhanced the complete spatial use of a road network by lowering average travel costs of vehicles with a 5-10 % reduction in traffic overhead over existing mechanisms. Additionally, the HMRM-ITS outperforms existing mechanisms in the form of packet transmission delay and throughput.

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Abstract:

Intelligent Transportation Systems (ITS) are required for efficient vehicle communication in the smart city. The goal of ITS was to provide a broad range of services in transportation, safety, comfort, commercial, mobility, and connectivity applications. In this era, road traffic is a major annoyance. The provision of real-time traffic information to drivers, in conjunction with a navigation system, can enable vehicles to choose the best route. To support ITS, this work proposes a Hybrid Multi-hop Routing Mechanism with Intelligent Transportation System (HMRM-ITS) for efficient communication among vehicles in vehicular ad hoc networks (VANETs). The proposed HMRM-ITS employs the multi-hop routing concept to enable vehicles to improve their driving performance and road safety. Furthermore, the proposed HMRM-ITS allows the transportation organization to communicate instantly between vehicles to Road-Side Units (RSUs), as well as vehicles-traffic servers in an efficient manner. The proposed mechanism enhanced the complete spatial use of a road network by lowering average travel costs of vehicles with a 5-10 % reduction in traffic overhead over existing mechanisms. Additionally, the HMRM-ITS outperforms existing mechanisms in the form of packet transmission delay and throughput.

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Abstract



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I. Introduction

II. System Architecture

III. Methodology

IV. Results and Discussion

V. Conclusion

VI. References

Abstract: The Internet of Things (IoT) has firmly established itself as a popular technology. It strives to make it easier for people across domains to live an "Easy & Smart" lifestyle. Machine vision and artificial intelligence (AI) are the sources of the idea of image recognition. Chronic illnesses, a catch-all phrase for conditions including Alzheimer's, Parkinson's, other types of dementia, cardiovascular disorders, and more, are on the rise. They come with challenges relating to ongoing supervision, care, and aid. Not everyone is prepared to handle the financial and ethical issues involving patients and their caretakers. Wearable IoT devices and AI offer a potential quick aid for dependable remote monitoring and help through ambient medical aid without jeopardizing the patient's confidentiality or privacy. The proposed work seeks to design a prototype that is inexpensive and provides pleasant patient healthcare. Concerning Alzheimer's, applications and IoT and AI devices are used to create a long-term fix. The patient will be able to recognize familiar people around them and capture knowledge for future reminders with the use of the proposed wearable camera-aided device in conjunction with a Bluetooth ear-complementary device. The AI component triggers constant reminders, which helps the patient stay more aware of their surroundings & situation.

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Date Added to IEEE Xplore: 01 August 2023

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Problem Solving and Python Programming

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III. Proposed Method

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V. Conclusion

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Abstract: Pervasive computation plays an integral part in WBANs. Along with pervasive methodologies, bio-sensors are available in a range of shapes and sizes, and depending on the state of the patient, multiple sensors can be inserted in, on, or around the human body to monitor, store, and relay vital signs for further investigation, judgments, and treatment. The tracking of patients' vital signs, as well as the time it takes to generate results, are essential components of the WBAN's integration into ubiquitous computing technologies. To ensure low power consumption, high precision of collected data, low latency, high efficiency, higher throughput with efficient bandwidth utilization, and synchronization with other systems and at the same time data must be stored and exchanged with care. To function successfully, a WBAN must first measure the quantity of electricity the device utilizes and then impose energy-efficient operating strategies. Current routing processes, such as the Stable Increased-Throughput Multi-hop Protocol for Link Efficiency (SIMPLE) and Mobility-supporting Adaptive Threshold-based Thermal-aware Energy-efficient Multi-hop Protocol (M-ATTEMPT), can be employed in WBANs by incorporating confidence measures into both the sensor data being monitored and the power levels needed for effective data broadcast to reach the sink. In contrast to Expected Transfers (ETX), this protocol avoids continuous communications and only forwards data of interest to the sink, resulting in minimal power usage and thereby increasing network reliability time, overall network lifetime, throughput, and end to end latency to 0.915 mw, 290 bits/s, and 250 ms, respectively.

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Prediction of Infant Growth using the Random Forest Algorithm

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Abstract: Every parent is curious about their child's internal and exterior development. Childhood is the first stage of a person's existence. To comprehend and better explain many elements of action, including the emotional, physical, social, intellectual, perceptual, and personality development, extensive research has been done in the past. Child development analysis is a scientific approach to evaluate growth, change, and stability. By learning more about how and why individuals develop and grow, one may better understand and meet a child's needs, allowing them to realize their full potential. Child development has a broad scope and a general purpose. However, just a few studies on early childhood development have been conducted. The project's objective is to use machine learning algorithm to forecast a child's future learning behavior and talents using a random forest algorithm and data-mining approach.

Published in: 2023 3rd International Conference on Advance Computing and Innovative Technologies in Engineering (ICACITE)

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ISBN Information:

Publisher: IEEE

Conference Location: Greater Noida, India

Contents

I. Introduction

The scientific study of the patterns of growth, change, and stability that occur from conception through puberty is known as child development. It explains how a youngster develops the ability to perform complicated tasks as he grows older [1]. Child development research is essential in a variety of fields,



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IoT based Innovative Teaching Learning using Smart Class Rooms

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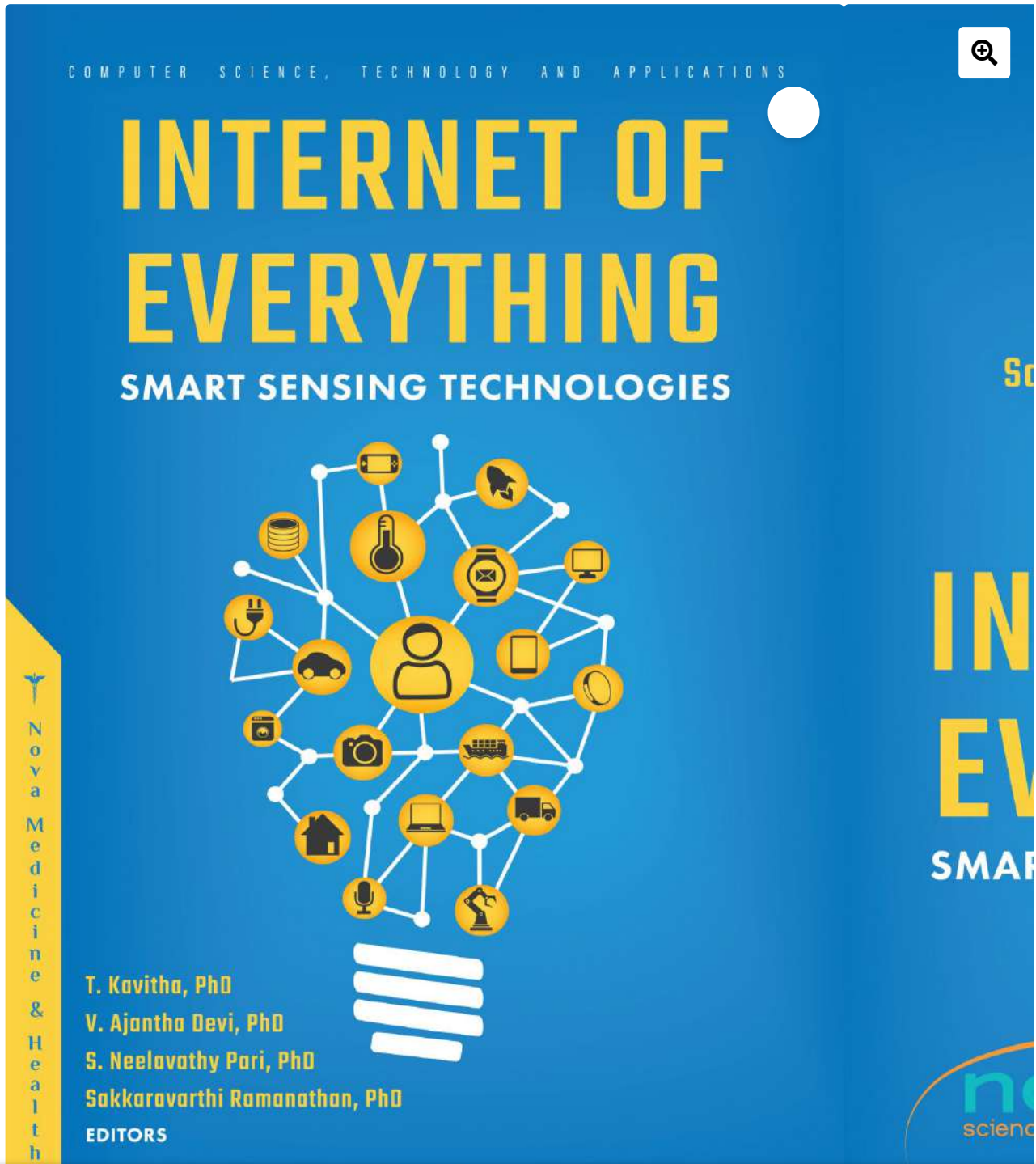
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The APT Cyber Warriors With TTP Weapons to Battle: An Review on IoT and Cyber Twin

Diana Arulkumar, Kartheeban K., Arulkumaran G.

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Abstract

Due to the blooming of Industrial 4.0 such as internet of things (IoT), cloud computing, industrial IoT (IIoT), and artificial intelligence (AI), with their innovative ideas and opportunities, the cyber attacker's modus operandi against the cyber defense triage is incredible. The genre of advanced persistent threat (APT) actors/group are equipped with sophisticated and substantial resources of tools, techniques, and procedure (TTP) at a breakneck pace. The IoT gadgets such as sensors, intelligent devices, and various rapidly emerging resources with energy, memory, and processing power are exponentially prone to multiple vulnerabilities. The nature of IIoT prompts heterogenous and rapid changes ranging the vulnerabilities from simple to complex attacks. APT menace follows the covert TTPs to target the asset of any organization like the government, military, or financial industry.

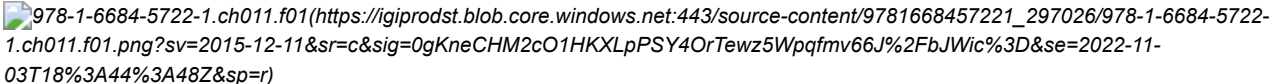
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Top

Background

In order to categorize the identity of attackers, in 2006 APT Phrase is framed by U.S. Airforce Analysts. The characteristics of an APT attackers are well skilled and persistent, equipped with sophisticated resources and targeted. The APT attackers launch an attack in multi stages. The APT is multi stage model. Quintero-Bonilla .et.al,2020 says, that the APT life cycle model consists of three-stages with Initial compromise (IC), Lateral movement, command &control(C2C), intrusion kill chain (IKC) is a four-stage model Information Collection, Intrusion phase, Lateral expansion, Information theft phase, 4 Stages Initial Compromise, C&C, Lateral movement, Attack achievement. This model called attack chain which comprises five Stages such as Reconnaissance, Incursion, Discovery, Capture, Ex-filtration. 5 Stages Delivery, Exploit, Installation, C&C, Actions. Attackers once after run a malware and exploit the zero -day vulnerability, access the network through the compromised computer to achieve the default goals. This life cycle based on the intrusion kill chain model which consists of 6Stages like Reconnaissance, weaponization, Delivery, Initial intrusion, C&C, Lateral movement, Data ex-filtration. The Lockheed Martin company designed a life cycle called cyber kill chain CKC, to understand the attackers TTP, they proposed 7 Stages Research, Preparation, Intrusion, conquering network, hiding presence, gathering data, Maintaining access. (Formerly Mandiant) the FireEye, after done penetrated testing of the APT1 campaign, it concluded with 8 Stages Initial recons, Initial, compromise, establish foothold, Escalate, privileges, Internal recon, move laterally, Maintain presence, Complete mission. The ATT and CK Focuses on the tactics based on the cyber threat actor who wants to accomplishes strategic goal and it classifies into 11 Stages such as Initial access, Persistence, Privilege Escalation, Discovery, Lateral movement, Collection, Exfiltration Stages executed in parallel: Execution, Defence evasion, Credential access, and Command &Control.

Figure 1. A survey from 2018 to 2021 of cyber threats Challenges on IIoT

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Abstract: This research proposes the design of an optical sensor that may be used to identify the presence of bacteria in contaminated water. We have taken a 2D photonic crystal structure into consideration for the design of the proposed sensor. An MIT-MEEP simulation tool is used to analyse the sensor. Studying the optical characteristics of various bacteria in water allows us to provide the refractive index value as an input to MEEP. Different bacteria's final responses to the proposed structure are analysed. The photonic crystal's refractive index profile changes when bacteria's refractive index varies. Because of the variation in bacteria's refractive index, the central frequency and wavelength are affected. The change in refractive index can be picked up by recording changes in the wavelength and frequency of the light transmitting through the structure. The analysis of the transmission and reflection spectra is made by using the MIT Electromagnetic Equation Propagation (MEEP) simulation tool. As bacteria's refractive index changes, it is shown that the wavelength and frequency shifts are significant.

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Authors

Figures

References

Keywords

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- III. Flat Wheel Finite Element Method
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Abstract:As there are many ways of locomotion in many parts of the country, but the most common and the least expensive locomotion for travelling and transporting heavy goods from one place to another place are railways, the most preferred ones. As the country develops, the transportation also develops from time to time. The most main criteria for improvement in railways are to improve the contact system of railway wheel to the tacks. A constant and consistent study on the rail-wheel system contact was tested for improve the values of railways. Our paper presents the finite element analysis with a rail-wheel model to get more accurate values of flat wheel contact. Optical sensors like fiber Bragg grating sensors gives the wavelength shift for various train conditions unloaded 22.3t to 70t, with sensitivity of 1.39 pm/ $\mu\epsilon$. This work gives idea on the improved process of the setup and the synthesis of the prospective exploratory techniques followed by ascendable, automotive, and working analysis.

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Date Added to IEEE Xplore: 04 May 2023

Publisher: IEEE

ISBN Information:

Conference Location: New Delhi, India

Contents

I. Introduction

Wheel-rail failure will result in a succession of catastrophes and untold economic loss, the wheel-rail conjoint has gradually become one of the alarming and important problems in the field of rail transportation. The flat wheel is one of the main types of potential minute causes for causing a wheel-rail failure, which happens as a result of significant unevenness of the wheel brought on by the wheels' prolonged braking and rolling. These wheel flats are inescapable and will result in extremely



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- I. Introduction
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Abstract:

A Brain Tumor is an abnormally growing clump of cells inside or around the brain, which can lead to a fatal situation if not detected at an earlier stage. Therefore, we present an Artificial Intelligence (AI) approach based on the YOLACT++ image segmentation model. In this technique, we introduced a two Dual attention network on the YOLACT++ architecture for the identification and segmentation of scanned MRI (Magnetic Resonance Imaging) for a brain tumor. We have applied the concepts of transfer learning by using RESNET-50 with Feature Pyramid Networks (FPN) as the backbone of our work. The experiment setup includes 400 images as a training set, and the results show that the proposed method achieved 94.71% segmentation accuracy for each segmentation. The proposed method is significantly higher than the previously published dice score of 88% for the Convolutional Neural Network (CNN) based approach.

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Abstract:Monitoring the temperature of disc brakes is crucial for ensuring their optimal performance in railway applications. To address this issue, a finite element analysis is conducted using Ansys software to assess temperature fluctuations in various parts of the brake under different conditions. Various factors such as payload, speed, and other variables can affect the braking mechanism and lead to brake failure. By installing a FBG sensor on the axle near the contact surface between the brake and the axle, it is possible to detect temperature changes as heat flows from the brake's outer frictional surface towards the axle. This is significant because a small temperature variation near the axle can have the same impact as a large temperature variation near the frictional surface.

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III. Methodology

IV. Conclusion

V. Limitations

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Monitoring the temperature of disc brakes is crucial for ensuring their optimal performance in railway applications. To address this issue, a finite element analysis is conducted using Ansys software to assess temperature fluctuations in various parts of the brake under different conditions. Various factors such as payload, speed, and other variables can affect the braking mechanism and lead to brake failure. By installing a FBG sensor on the axle near the contact surface between the brake and the axle, it is possible to detect temperature changes as heat flows from the brake's outer frictional surface towards the axle. This is significant because a small temperature variation near the axle can have the same impact as a large temperature variation near the frictional surface.

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Contents

I. Introduction

A rolling railway has kinetic energy, which must be utilized to stop the train. The simplest method to do this is to convert the energy into heat. In most cases, the change is achieved by applying a contact material to the rotating wheels or the axle-mounted discs. Friction is produced by the substance, which

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Technological Coefficient to Improve Research Development and Innovation Factors in the World

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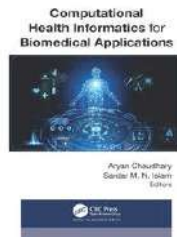
Abstract

The new concept to measure snowfall and sophistication examines the relationship of the Technological Coefficient (T); the variables are grouped into three dimensions: Education and training, snowfall; and institutional strength. The analyzed population corresponds to 116 countries. 158 variables per country were collected for ten years. For the analysis, information from The dataset of Global Competitiveness Index Historical 2008–2018 of the World Economic Forum was used, with index, coefficient values, country codes, global id, identified series, and treatments (Income Groups, Regions, and Forum Ranking). A quantitative approach with descriptive, correlational, deductive, inductive, analytical, and synthetic methods were used such as hypothesis testing, linear regression analysis, ANOVA, PCA, univariate variance, and eta square. The T coefficient positive correlation with Innovation and sophistication factors ($F = 5.202.18$; $\text{Sig} = .000$), was able to reduce the error by 98%; and it served to evaluate the three treatments analyzed. The means of the income groups differ significantly, $F(1,344) = 8.83$, $p < 001$, $\eta^2 = 0.07$ for the dependent variable of the Technological Coefficient (T). In addition, the means of the Regions differ significantly, $F(1,341) = 7.99$, $p < 001$, $\eta^2 = 0.12$. The value of Eta squared indicated a large effect of income groups and Regions on the T coefficient. This analysis confirmed the power of the T coefficient to identify the countries that maximize innovation and the sophistication of their markets.

Keywords

Innovation **business sophistication** **intellectual property**

Chapter




Photonic MEMS Sensor for Biomedical Applications

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This study presents a novel photonic crystal (PC) pressure sensor design and three-dimensional (3D) modeling and simulation for three different structures. A 2D PC slab based on silicon is used to implement the device on a SiO₂ substrate. Using Ansys Workbench and the Rsoft Optical tool, strain/stress simulations, as well as spectrum simulations, are carried out. In this study, the deformation of various structures, including rectangular, circular, and square diaphragms, as well as variations in refractive index are taken into account when calculating the sensitivity of the suggested pressure sensor. The numerical findings demonstrate that when pressure is applied, the refractive index fluctuations increase the transmission spectrum's resonant wavelength while the deformation factor decreases it. It has been demonstrated that there is a linear relationship between the applied pressure and the intended micro-resonant cavity's wavelength. The square diaphragm has shown maximum sensitivity compared to other structures. For the minimum detectable applied pressure of 0.5 Pa, the simulation result shows that for the three types of datagrams rectangle, square, and circular it is found that there is a distinct shift in wavelength. For the circular diaphragm's shift in wavelength is 742 μm, whereas the rectangle and square observed shift in wavelength is 956 μm and 1016 μm respectively. This can be applied in biomedical applications. The proposed sensor system has shown feasibility for future fabrication.

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Contents

I. Introduction

ROBOTIC HAND GESTURE

Dr.MANJULA C¹, Ms.SEEMA V² , Mr.JAIDEEP R³

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Abstract— This paper presents a new approach for controlling robotic hand gestures With the help of this technique one can pose a hand gesture in the vision range of a robot and corresponding to this notation, desired action is performed by the robotic system. Real-time hand tracking technique is used for object detection in the range of vision.

I. INTRODUCTION

A Gesture Controlled robot is a robot which can be controlled by your hand gestures. You just need to have a small transmitting device in your hand, which included an acceleration meter to transmit an appropriate command to the robot so that it can do whatever we want.

A gesture-controlled robot is controlled by using the hand in place of any other method like buttons or joystick. Here one only needs to move the hand to operate the robot. A transmitting device is placed in the user's hand, which contains the RF Transmitter and accelerometer to transmit a command to the robot so that it can perform the required task of moving forward, back, turning left, right and stop. These tasks will be identified using the hand gesture.

II. LITERATURE SURVEY

[1] "Robotics and Automation in the Food Industry: Current Status and Future Perspectives" by M. Manfredottietal. This review article discusses the current state of robotics and automation in the food industry, including the use of robotic arms for tasks such as packaging, sorting, and palletizing.

There are number of methods available to clean the inside of the closed pipeline namely traditional method like boiling, picking, alcohol and salt and cleaning kits, or tools kits such as wire and plunger or large-gauge snake. However, all the methods can over-stress older pipeline and cause leaks that make even more extensive repair.

[2] "Design and Control of a Robotic Arm: A Review" by S. P. Mohanty. This paper provides a comprehensive review of the design and control of robotic arms, including kinematics, dynamics, and control algorithms.

[3] "A Survey on Robotic Arms for Service Robots" by Y. Zhang. This article reviews the current state of robotic arms for service robots, which are designed to interact with humans in various settings such as healthcare, education, and entertainment.

[4]. "Robotics and Automation in Construction: A Review of 3D Printing, Robotics, and Autonomous Systems" by J. Chen .This review paper discusses the use of robotic arms in construction applications, including 3D printing, bricklaying, and demolition.

[5]. "Design and Control of Robotic Arms for Rehabilitation and Assistive Technology: A Review" by F. C. Chen. This article reviews the use of robotic arms for rehabilitation and assistive technology applications, including prosthetics, exoskeletons, and wheelchairs

[6]. "Advances in Robotic Arm Design and Control for Precision Agriculture" by J. Chen This paper reviews the use of robotic arms in precision agriculture applications, including planting, harvesting, and spraying.

[7]. "A Review of Robot Manipulators: Dynamics, Control, and Applications" by M. W. Spong.This book provides a comprehensive overview of robot manipulators, including robotic arms, and covers topics such as kinematics, dynamics, and control.

Overall, these literature surveys provide an overview of the current state of research and development in the field of robotic arms, and highlight the various applications and challenges associated with this technology.

III MATERIALS and METHODOLOGY

The AT89S8252 is a low power, high-performance CMOS 8-bit microcontroller with 8K bytes of in-system programmable Flash memory. It is associated with circuitry like Crystal with capacitors, Reset circuitry, Pull up resistors (if needed) and so on.

The microcontroller controls the devices being interfaced and communicates with the devices according to the program being written. Maintaining the Integrity of the Specifications.

TRANSMITTER

The transmission section consists of three modules. They are ADC Converter, Encoders, Accelerometer and an RF Transmitter.

POWER SUPPLY

The input to the circuit is from the regulated power supply the AC input, i.e., 230V from the mains supply is stepped down using a transformer to 12V and is fed to a rectifier. The output got from a rectifier is a pulsating voltage. The output voltage from the rectifier is given to a filter to remove any AC noise. Now, this voltage is given to a voltage-regulator to obtain a pure dc voltage.

VOLTAGE REGULATORS

Voltage regulator ICs come with fixed or varying output voltages. Most regulators include automatic protection from excessive current ('overload protection') and overheating ('thermal protection'). The LM7805 is easier to use, you simply connect the positive of your DC power supply to an Input pin, connect the negative to the Common pin and then when you turn on the power, you get a 5-volt supply from the output pin.



Fig. 1: components assembled

Gesture controlled robot moves according to the user's hand movement recognized by the device in our hand.

When we tilt hand in front side, the robot starts to moving forward and continues moving forward until the next command is given.

When we tilt hand in the backside, the robot changes its state and start moving in the backwards direction until another command is given.

When we tilt it towards the left side, it will turn left till next command. When we tilt our hand in right side robot is turned to the right.

Fig. 2: Bluetooth device.



A HC-06 is the popular Bluetooth module as in Fig. 3. This HC06 module is slave mode only. It's very easy to add wireless serial connectivity for your device with this module.

Examples for Arduino and other boards are available. Once you pair with other Bluetooth devices you work like with normal UART to exchange data.

This module has built-in 3.3V voltage regulator and helps to break out the important pins (Vcc, Gnd, Txd, Rxd). Based on CSR BC4 chip, Bluetooth V2.0 + EDR.

You can set the baud rate, name and pair password by AT commands when there is no Bluetooth connection. This module is a slave- it can be paired with Computer- Bluetooth master- mobile phone- PDA- PSP and so on.

IV.METHODOLOGY

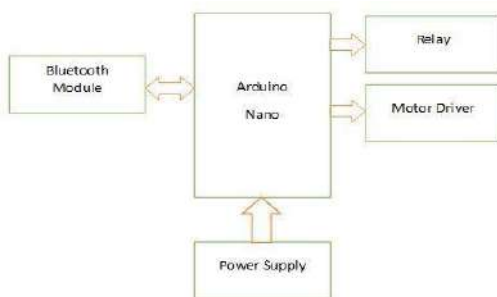


Fig 3: Block diagram

This block diagram consists of Arduino Nano, Bluetooth module, relay, motor driver and powersupply.

The Arduino Nano as in Fig. 5 is Arduino's classic breadboard friendly designed board with the smallest dimensions. The Arduino Nano comes with pin headers that allow for an easy attachment onto a breadboard and features a Mini-B USB connector.

The classic Nano is the oldest member of the Arduino Nano family boards. Arduino is an open hardware development board that can be used by tinkerers, hobbyists, and makers to design and build devices that interact with the real world.

The movement of the DC motor can be controlled by the bluetooth module, its work based on the Arduino nano fixed in the circuit.

A Gesture Controlled robot with Arduino Uno microcontroller has been designed during this work, which may be controlled by human hand gestures.

This needs to wear a little transmitting device on our hand included an accelerometer, which transmits particular commands to the robot to maneuver consistent with the users hand gesture and one receiver at the robot. The RF module usually works at a frequency of 434MHZ and also it has a range of 100meters.

The transmission occurs at the rate of 1Kbps-10Kbps. The transmitted data is received by the RF receiver operated at the same frequency as that of the transmitter. Transmission through RF(Radio frequency) is always better than IR(Infrared).

Circuit for this hand gesture-controlled robot is quite simple. An RF pair is used for communication and connection to the Arduino. The motor driver is connected with the Arduino to operate the robot. Motor driver's input pins 2, 7, 10 and 15 are connected to Arduino digital PIN 6, 5, 4 and 3. Here we are using used two DC motors to drive the robot in which one motor is connected at the output of motor driver 3 and 6, and another motor is connected at 11 and 14. A 9-volt battery is also used to power the motor driver for driving motors.

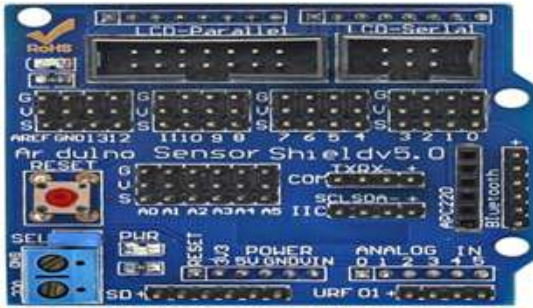


Fig 4: Circuit Diagram

This block diagram consists of Arduino Nano, Bluetooth module, relay, motor driver and powersupply. The Arduino Nano as in Fig. 4 is Arduino's classic breadboard friendly designed board with the smallest dimensions.

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The movement of the DC motor can be controlled by the bluetooth module, its work based on the Arduino nano fixed in the circuit.

The circuit fixed to the bread board and movement control can be operated with the bluetooth RC controller.

It requires Basic Python code to connect the bluetooth module, the python program dumped to the circuit.

The Arduino Nano is a small, complete, and breadboard-friendly board based on the ATmega328 (Arduino Nano 3.x).

It has more or less the same functionality of the Arduino Duemilanove but in a different package.

It lacks only a DC power jack, and works with a Mini-B USB cable instead of standard one.

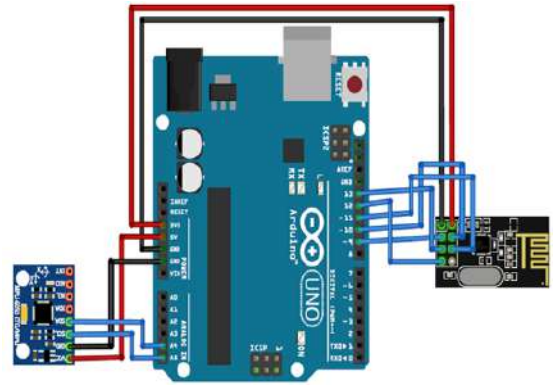


Fig 5: Circuit Diagram with bluetooth

- Arduino Uno (or an Arduino with enough Analogue input pins to support all the sensors)
- 20kg-cm torque Servos for wrist movement
- 2kg-cm torque Servos for fingers
- Atleast 40kg-cm torque servo for elbow and shoulder
- Arduino Sensor Shield

V. CONCLUSIONS

In this paper, we introduced a hand-gesture-based interface for navigating a car-robot. A user can control a car-robot directly by using his or her hand trajectories.

In the future, we will directly use a mobile phone with an accelerometer to control a car-robot.

We also want to add more hand gestures (such as the curve and slash) into the interface to control the car more naturally and effectively.

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